

TO: MSPM Distribution
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The MSPM sections BG.3.00 - BG.3.05 replace section BG.3 and reflect a reorganization of the Segment Control Module. In general the functions of Segment Control are unchanged with the following two exceptions: some of the information retrieving primitives such as getsegno, getname, segstatus, setseglock, newmode, and oldmode no longer exist as these functions have been moved to the Segment Management Module (BD.3), and a new set of primitives have been added, the Ring Simulation Module, to handle ring changing and validation functions. Otherwise the only changes are implementation details, some primitive names and arguments.

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Identification

Introduction to Segment Control
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Purpose

Segment control maintains records of all segments known to the current process and makes these segments available to the process upon request. Information concerning these segments is maintained in the known segment table (KST) which is manipulated exclusively by segment control. Segment control also provides information concerning active segments in the active segment table (AST) and the descriptor segment table (DST) for the exclusive use of segment control and page control. In addition, segment control maintains an entry in the process segment table (PST) for each process which is currently active (see BJ.9.01).

Introduction

Segment control is divided into five separate modules, the System Interface Module, the User Interface Module, the Process Load Module, the Segment Utility Module, and the Ring Register Simulation Module. The following list gives a brief description of the functions of these modules.

1. The system interface module - This module contains primitives which are privileged and provided for the use of other supervisory procedures and the backup and multilevel systems (see Section BG.3.01 of this manual).
2. The user interface module - This module contains all of the unprivileged primitives of segment control. These primitives provide various service functions for the user relating to segments already known to his process. The user interface module is fully specified in section BG.3.02 of this manual.

3. The process load module - This module provides primitives for the use of various modules of the hard-core supervisor. These primitives are specifically designed to assist in the loading and unloading of processes. The process load module is fully specified in section BG.3.03 of this manual.
4. The segment utility module - This module consists of several primitives which are provided for the exclusive use of segment control procedures. These primitives are provided primarily to assist in the manipulation of the AST and KST. The segment utility module is fully specified in section BG.3.04 of this manual.
5. The ring register simulation module - This module is separated from the others only to minimize the changes in the file system when and if a ring register is added to the 645. It will go away if this hardware becomes available. The ring register simulation module is specified in section BG.3.05 of this manual.

Errors

In all of the primitives of segment control, the last argument in the calling sequence is an error code. If a called procedure detects no errors in its work, this argument will be set to zero on return; if an error is detected, it will contain an error number which encodes the type of error and the procedure which detected it. It is the responsibility of the caller to test the error code and take the appropriate action.

A list of all the error codes used by the basic file system is contained in section BG.14.